Symmetric Triangle Quadrature Rules for Arbitrary Functions

Brian A. Freno, William A. Johnson, Brian F. Zinser, Salvatore Campione Sandia National Laboratories

> Donald R. Wilton Francesca Vipiana University of Houston Politecnico di Torino

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- Singularities
- Approach 1: Optimization for Moderate Number of Functions
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 - Challenges to Generate
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Overview	7					

- Gaussian quadrature rules are useful for numerical integration
- For integrands accurately approximated by polynomials, rules are typically employed that exactly integrate polynomials





- Quadrature rules for triangles are important for evaluating surface integrals
- Several authors have developed methods for computing symmetric quadrature rules for polynomials

Lyness & Jespersen (1975), Dunavant (1985), Wandzura & Xiao (2003), Papanicolopulos (2015)

- Geometrically symmetric rules are desirable
 - Mapping is straightforward
 - Points are not more concentrated at a single vertex





- Polynomial rules do not converge monotonically or rapidly for integrable functions with boundary singularities
- Such functions include unbounded derivatives at the boundary, where the function may not be defined
- For 1D, an approach has been developed to compute quadrature rules for singular functions

Ma et al. (1996)

• For 2D, previous authors have taken the outer product of one-dimensional rules to generate asymmetric triangle rules

Vipiana et al. (2013)





- Regardless of dimension and function sequence, equations for computing quadrature rules are stiff and highly dependent upon initial guess
- In multiple dimensions, for a given number of points, the number of functions that can be integrated is unknown



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 - Polynomial Integration
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• An *n*-point quadrature rule exactly integrates a sequence of n_f functions $\mathbf{f}(\mathbf{x}) = \{f_1(\mathbf{x}), \dots, f_{n_f}(\mathbf{x})\}$, such that

$$\int_{A} \mathbf{f}(\mathbf{x}) dA = \sum_{i=1}^{n} w_i \mathbf{f}(\mathbf{x}_i)$$

- In 1D, $n_f = 2n$ and, for polynomials, $\mathbf{f}(x) = \{1, \dots, x^{2n-1}\}$
- In 2D, $n_f \stackrel{?}{=} 3n$,
 - This is unproven
 - If rules are symmetric, the efficiency can be significantly lower



- Invariant to rotation and reflection about the medians for equilateral triangles
- Triangles can be isoparametrically transformed to other triangles
- Rules are constructed from a combination of orbits, such that $n=n_0+3n_1+6n_2$





- Rules that integrate polynomials of degree d exactly integrate linear combinations of $x^p y^q$
 - -0 < p, q < d
 - 0
 - $-n_f = (d+1)(d+2)/2$ monomials
- This can yield more equations than unknowns
 - A 3-point rule can integrate polynomials of $d = 2 \rightarrow n_f = 6$ monomials: $\mathbf{f}(x, y) = \{1, x, y, x^2, y^2, xy\}$
 - Number of unknowns is 2: α (position along median) and w (weight)
 - Mismatch is reconcilable; 6 quadrature equations are not linearly independent



Preliminaries 0000 Polynomial Integration (continued)

- For polynomials, an invariant sequence can be constructed to reduce number of equations
- Alternatively, we can formulate problem as unconstrained optimization problem in barycentric coordinates:

 $\arg\min F(\boldsymbol{\alpha},\boldsymbol{\beta},\mathbf{w}),$ $\alpha \beta w$

where

$$F(\boldsymbol{\alpha},\boldsymbol{\beta},\mathbf{w}) = \sum_{j=1}^{n_f} \left(\frac{\tilde{I}_{f_j} - I_{f_j}}{I_{f_j}}\right)^2,$$

$$\tilde{I}_{f_j} = \sum_{i=1}^n w'_i f_j(\alpha_i, \beta_i), \qquad I_{f_j} = \int_0^1 \int_0^{1-\beta} f_j(\alpha, \beta) d\alpha d\beta,$$

with the expectation that $F(\boldsymbol{\alpha}, \boldsymbol{\beta}, \mathbf{w}) = 0$



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 - Two-Dimensional Characterization
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- Integrands with boundary singularities can have singularities located on edges and/or corners
 - Derivatives of integrand are unbounded
 - Integrand can be defined or undefined, provided the integrand is integrable





- Series expansion about singularity location
- Expansion alternates between monomials and singularities
- For the electric-field integral equation,

 $\mathbf{f}(x) = \{1, x, x \ln x, x^2, x^3, x^3 \ln x, x^4, x^5, x^5 \ln x, \ldots\}$





- Expansions alternate between monomials and singularities
- If 2D characterizations of singularities are known, can use in sequence
- For the electric-field integral equation,

$$\begin{array}{c} 1\\ x\\ x\\ x\ln \left(y-1+\sqrt{x^2+(y-1)^2}\right)\\ x\ln \left(y+\sqrt{x^2+y^2}\right)\\ x^2, xy\\ x^3, x^2y\\ x^3\ln \left(y-1+\sqrt{x^2+(y-1)^2}\right)\\ x^3\ln \left(y+\sqrt{x^2+y^2}\right)\\ x^4, x^3y, x^2y^2\\ x^5, x^4y, x^3y^2\\ x^5\ln \left(y-1+\sqrt{x^2+(y-1)^2}\right)\\ x^5\ln \left(y+\sqrt{x^2+y^2}\right)\\ x^6, x^6y, x^4y^2, x^3y^3\\ x^7\ln \left(y-1+\sqrt{x^2+(y-1)^2}\right)\\ x^7\ln \left(y-1+\sqrt{x^2+(y-1)^2}\right)\\ x^7\ln \left(y+\sqrt{x^2+y^2}\right)\\ x^5, x^7y, x^6y^2, x^5y^4, x^4y^4\\ x^9, x^8y, x^7y^2, x^6y^3, x^5y^4 \end{array}$$



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- Goal is to efficiently integrate polynomials and singularities
- Compute points & weights through optimization nonlinear least squares •
- This approach uses polynomial rules as a baseline
 - Initial guesses near the polynomial rule
 - Same orbit counts for each n
- Replace higher polynomial degrees with singular functions
- Attempt to increase number of functions integrated







- Weigh number of singular functions against maximum polynomial degree
- Ability to integrate polynomials includes ability to integrate cross terms (e.g., x^3 includes x^2y)
- Ability to integrate singular functions does not extend to cross terms
- Three approaches to address this issue:
 - Use 2D characterization of singularity, if available
 - Use 1D characterization of singularity, assume cross terms are not essential
 - Include cross terms for 1D characterization and reduce polynomial degree
- Alternatively, one can use Approach 2



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- In multiple dimensions, number of integrable functions not straightforward
- Computation is expensive and multiple solutions exist
- For lengthy function sequences, we employ n'-point 1D rules that integrate 1D function sequences, such that $n = 3n'^2$



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 A_S has vertices (0 m, 0 m), (1/20 m, 1/20 m), and $(-1/20\,{\rm m}, 1/20\,{\rm m})$ A_T has same shape

Approach 1 Function Sequences

1D Singularities	2D Singularities
1	1
x	x
$x \ln x$	$x\ln(y-1+\sqrt{x^2+(y-1)^2})$
x^2, xy	$x\ln(y+\sqrt{x^2+y^2})$
x^3, x^2y	x^2, xy
$x^3 \ln x$	$x^3, x^2 y$
x^4, x^3y, x^2y^2	$x^{3}\ln(y-1+\sqrt{x^{2}+(y-1)^{2}})$
$x^5, x^4 y, x^3 y^2$	$x^3 \ln \left(y + \sqrt{x^2 + y^2}\right)$
$x^5 \ln x$	x^4, x^3y, x^2y^2
$x^6, x^5 y, x^4 y^2, x^3 y^3$	x^5,x^4y,x^3y^2
$x^7, x^6 y, x^5 y^2, x^4 y^3$	$x^{5}\ln(y-1+\sqrt{x^{2}+(y-1)^{2}})$
$x^7 \ln x$	$x^5 \ln \left(y + \sqrt{x^2 + y^2}\right)$
$x^8, x^7 y, x^6 y^2, x^5 y^3, x^4 y^4$	$x^6, x^5 y, x^4 y^2, x^3 y^3$
$x^9, x^8 y, x^7 y^2, x^6 y^3, x^5 y^4$	x^7,x^6y,x^5y^2,x^4y^3
$x^9 \ln x$	$x^{7}\ln(y-1+\sqrt{x^{2}+(y-1)^{2}})$
$x^{10}, x^9y, x^8y^2, x^7y^3, x^6y^4, x^5y^5$	$x^7 \ln \left(y + \sqrt{x^2 + y^2} \right)$



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Numerical Example















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$\mathbf{f}(x) = \{1, x, x \ln x, x^2, x^3, x^3 \ln x, x^4, x^5, x^5 \ln x, \ldots\}$









Case 1: Scalar potential, singular interaction, $\theta = 0^{\circ}$, $\Delta y = 0$, and $\Delta z = 0$





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Case 2: Scalar potential, singular interaction, $\theta = 45^{\circ}$, $\Delta y = 0$, and $\Delta z = 0$





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Case 3: Scalar potential, singular interaction, $\theta = 90^{\circ}$, $\Delta y = 0$, and $\Delta z = 0$



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Numerical Example

Case 4: Scalar potential, singular interaction, $\theta = 180^{\circ}$, $\Delta y = 0$, and $\Delta z = 0$



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Case 5: Scalar potential, near-singular interaction, $\theta = 180^{\circ}$, $\Delta y = 0$, and $\Delta z = \delta_z$



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Case 6: Scalar potential, far interaction, $\theta = 0^{\circ}$, $\Delta y = \delta_{y}$, and $\Delta z = 0$



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Case 7: Vector potential, singular interaction, $\theta = 90^{\circ}$, $\Delta y = 0$, and $\Delta z = 0$



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Case 8: Vector potential, singular interaction, $\theta = 180^{\circ}$, $\Delta y = 0$, and $\Delta z = 0$



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 - Concluding Remarks





- Introduced 2 symmetric quadrature approaches for arbitrary functions
- Motivated by need to integrate singular integrands
- Approach 1
 - Generally most efficient for singular integrands outperformed polynomial rules by orders of magnitude
 - Similar efficiency to polynomial rules for nonsingular integrands
- Approach 2
 - More efficient than polynomial rules for singular integrands
 - Error decreases monotonically relative to number of integration points
 - Points are cheap to compute (from 1D rules)



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