Code-Verification Techniques for Hypersonic Reacting Flows in Thermochemical Nonequilibrium

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Introduction	Equations	Spatial Accuracy	Spatial Results	Source Term	Source Results	Summary

• Introduction

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- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
- Thermochemical-Source-Term Verification Results
- Summary



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Hypersonic Flow

Hypersonic flows and underlying aerothermochemical phenomena

- Important in design & analysis of vehicles exiting/reentering atmosphere
- High flow velocities and stagnation enthalpies
 - Induce chemical reactions
 - Excite thermal energy modes
- Aerodynamic and thermochemical models require full coupling





Sandia Parallel Aerodynamics and Reentry Code (SPARC)

- Under development at Sandia National Laboratories
- Compressible computational fluids dynamics code
- Models transonic and hypersonic reacting turbulent flows
- Solves transient heat equation and equations associated with decomposing and non-decomposing ablators
- One- and two-way couplings between fluid-dynamics and ablation solvers



Verification and Validation

Credibility of computational physics codes requires verification and validation

- Validation assesses how well models represent physical phenomena
 - Computational results are compared with experimental results
 - Assess suitability of models, model error, and bounds of validity
- Verification assesses accuracy of numerical solutions against expectations
 - Solution verification estimates numerical error for particular solution
 - $-\ Code\ verification\ verifies\ correctness\ of\ numerical-method\ implementation$



Introduction	Spatial Accuracy	Source Term	Summary
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Code Verification

Code verification is focus of this work

- Governing equations are numerically discretized
 - Discretization error is introduced in solution
- Seek to verify discretization error decreases with refinement of discretization – Should decrease at an expected rate
- Use manufactured and exact solutions to compute error



Introduction	Spatial Accuracy		Summary
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Code Verification

Code verification demonstrated in many computational physics disciplines

- Fluid dynamics
- Solid mechanics
- Heat transfer
- Multiphase flows
- Electrodynamics
 - Electromagnetism
- Fluid–structure interaction
- Radiation hydrodynamics

Code-verification techniques for hypersonic flows have been presented

- Single-species perfect gas
- Multi-species gas in thermal equilibrium

We present code-verification techniques for hypersonic reacting flows in thermochemical **nonequilibrium** and demonstrate effectiveness

- Spatial discretization
- Thermochemical source term



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- Governing Equations
 - Conserved Quantities
 - Vibrational Energy
 - Translational–Vibrational Energy Exchange
 - Chemical Kinetics
 - Scope of Code Verification
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
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Conservation of mass, momentum, and energy:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right),$$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{cases}, \quad \mathbf{F}_c \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{bmatrix}, \quad \mathbf{F}_p \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^T \\ \mathbf{0}^T \end{bmatrix}, \quad \mathbf{F}_d \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{bmatrix},$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad \begin{aligned} & \boldsymbol{\rho} = \{\rho_1, \dots, \rho_{n_s}\}^T, \quad & \dot{\mathbf{w}} = \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T : \text{mass production rates per volume,} \\ & \boldsymbol{\theta} = \sum_{s=1}^{n_s} \rho_s, \quad & e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s}: \text{ mixture vibrational energy per mass,} \\ & p = \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R}T, \quad & \mathbf{e}_v = \{e_{v_1}, \dots, e_{v_{n_s}}\}^T: \text{ vibrational energies per mass,} \\ & Q_{t-v}: \text{ translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Conservation of mass, momentum, and energy:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right),$$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \boldsymbol{\rho} \mathbf{v} \\ \boldsymbol{\rho} \boldsymbol{E} \\ \boldsymbol{\rho} \boldsymbol{e}_{v} \end{cases}, \quad \mathbf{F}_{c} \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^{T} \\ \boldsymbol{\rho} \mathbf{v} \mathbf{v}^{T} \\ \boldsymbol{\rho} \boldsymbol{E} \mathbf{v}^{T} \\ \boldsymbol{\rho} \boldsymbol{e}_{v} \mathbf{v}^{T} \end{bmatrix}, \quad \mathbf{F}_{p} \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ \boldsymbol{p} \mathbf{I} \\ \boldsymbol{p} \mathbf{v}^{T} \\ \mathbf{0}^{T} \end{bmatrix}, \quad \mathbf{F}_{d} \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{h})^{T} \\ (-\mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{e}_{v})^{T} \end{bmatrix},$$

Multiple species

$$\begin{split} \mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad & \mathbf{p} = \{\rho_1, \dots, \rho_{n_s}\}^T, \quad & \dot{\mathbf{w}} = \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T \text{: mass production rates per volume,} \\ \mathbf{p} = \sum_{s=1}^{n_s} \rho_s, \quad & e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s} \text{: mixture vibrational energy per mass,} \\ & p = \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R}T, \quad & \mathbf{e}_v = \{e_{v_1}, \dots, e_{v_{n_s}}\}^T \text{: vibrational energies per mass,} \\ & Q_{t-v} \text{: translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



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Conservation of mass, momentum, and energy:

$$\begin{split} & \overset{\text{Local time derivative}}{\frac{\partial \mathbf{U}}{\partial t}} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right), \end{split}$$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \boldsymbol{\rho} \mathbf{v} \\ \boldsymbol{\rho} \mathbf{E} \\ \boldsymbol{\nu} \mathbf{v}^T \\ \boldsymbol{\rho} \mathbf{e} \\ \boldsymbol{v} \mathbf{v}^T \\ \boldsymbol{\rho} \mathbf{v} \\ \boldsymbol{v}^T \\ \boldsymbol{\rho} \mathbf{v} \\ \mathbf{v}^T \\$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \{\rho_{1}, \dots, \rho_{n_{s}}\}^{T}, \quad \dot{\mathbf{w}} = \{\dot{w}_{1}, \dots, \dot{w}_{n_{s}}\}^{T} : \text{mass production rates per volume,} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \sum_{s=1}^{n_{s}} \rho_{s}, \quad e_{v} = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{\rho} e_{v_{s}} : \text{mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{M_{s}} \bar{R}T, \quad \mathbf{e}_{v} = \{e_{v_{1}}, \dots, e_{v_{n_{s}}}\}^{T} : \text{vibrational energies per mass,} \\ Q_{t-v} : \text{translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Conservation of mass, momentum, and energy:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}(\mathbf{U}) = -\nabla \cdot \mathbf{F}_{p}(\mathbf{U}) + \nabla \cdot \mathbf{F}_{d}(\mathbf{U}) + \mathbf{S}(\mathbf{U})$$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \rho \mathbf{v} \\ \rho E \\ \rho e_{\boldsymbol{v}} \end{cases}, \quad \mathbf{F}_{\boldsymbol{c}} \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^{T} \\ \boldsymbol{\rho} \mathbf{v} \mathbf{v}^{T} \\ \boldsymbol{\rho} E \mathbf{v}^{T} \\ \boldsymbol{\rho} e_{\boldsymbol{v}} \mathbf{v}^{T} \end{bmatrix}, \quad \mathbf{F}_{\boldsymbol{p}} \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^{T} \\ \mathbf{0}^{T} \end{bmatrix}, \quad \mathbf{F}_{\boldsymbol{d}} \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{\boldsymbol{v}} - \mathbf{J}^{T} \mathbf{h})^{T} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{\boldsymbol{v}} - \mathbf{J}^{T} \mathbf{h})^{T} \end{bmatrix},$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad \begin{pmatrix} \rho = \{\rho_1, \dots, \rho_{n_s}\}^T, & \dot{\mathbf{w}} = \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T : \text{mass production rates per volume,} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad \begin{pmatrix} \rho = \sum_{s=1}^{n_s} \rho_s, & e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s} : \text{ mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R}T, & \mathbf{e}_v = \{e_{v_1}, \dots, e_{v_{n_s}}\}^T : \text{ vibrational energies per mass,} \\ Q_{t-v} : \text{ translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Conservation of mass, momentum, and energy:

Pressure flux gradient

 $\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right),$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{cases}, \quad \mathbf{F}_c \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{bmatrix}, \quad \mathbf{F}_p \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^T \\ \mathbf{0}^T \end{bmatrix}, \quad \mathbf{F}_d \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{bmatrix},$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \{\rho_{1}, \dots, \rho_{n_{s}}\}^{T}, \quad \dot{\mathbf{w}} = \{\dot{w}_{1}, \dots, \dot{w}_{n_{s}}\}^{T} : \text{mass production rates per volume,} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \sum_{s=1}^{n_{s}} \rho_{s}, \quad e_{v} = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{\rho} e_{v_{s}} : \text{mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{M_{s}} \bar{R}T, \quad e_{v} = \{e_{v_{1}}, \dots, e_{v_{n_{s}}}\}^{T} : \text{vibrational energies per mass,} \\ Q_{t-v} : \text{translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$

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Conservation of mass, momentum, and energy:

Diffusive flux gradient

 $\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right),$

where

$$\mathbf{U} = \begin{cases} \rho \\ \rho \mathbf{v} \\ \rho E \\ \rho e_{v} \end{cases}, \quad \mathbf{F}_{c} \left(\mathbf{U} \right) = \begin{bmatrix} \rho \mathbf{v}^{T} \\ \rho \mathbf{v} \mathbf{v}^{T} \\ \rho E \mathbf{v}^{T} \\ \rho e_{v} \mathbf{v}^{T} \end{bmatrix}, \quad \mathbf{F}_{p} \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^{T} \\ \mathbf{0}^{T} \end{bmatrix}, \quad \mathbf{F}_{d} \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{h}) \\ (-\mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{e}_{v})^{T} \end{bmatrix},$$

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$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Equations Spatial Accuracy 00000 Governing Equations: n_s Species in Vibrational Nonequilibrium

Thermochemical source term

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right),$$

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$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \boldsymbol{\rho} \mathbf{v} \\ \boldsymbol{\rho} E \\ \boldsymbol{\rho} e_v \end{cases}, \quad \mathbf{F}_c \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^T \\ \boldsymbol{\rho} \mathbf{v} \mathbf{v}^T \\ \boldsymbol{\rho} E \mathbf{v}^T \\ \boldsymbol{\rho} e_v \mathbf{v}^T \end{bmatrix}, \quad \mathbf{F}_p \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ \boldsymbol{\rho} \mathbf{I} \\ \boldsymbol{p} \mathbf{v}^T \\ \mathbf{0}^T \end{bmatrix}, \quad \mathbf{F}_d \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{bmatrix},$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \{\rho_{1}, \dots, \rho_{n_{s}}\}^{T}, \quad \dot{\mathbf{w}} = \{\dot{w}_{1}, \dots, \dot{w}_{n_{s}}\}^{T} : \text{mass production rates per volume,} \\ \mathbf{v} = \left\{ \begin{array}{c} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{array} \right\}, \quad \begin{array}{l} \rho = \sum_{s=1}^{n_{s}} \rho_{s}, \quad e_{v} = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{\rho} e_{v_{s}} : \text{mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{M_{s}} \bar{R}T, \quad \mathbf{e}_{v} = \left\{ e_{v_{1}}, \dots, e_{v_{n_{s}}} \right\}^{T} : \text{vibrational energies per mass,} \\ Q_{t-v} : \text{translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



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Vibrational Energy

Mixture vibrational energy per mass:

$$e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s},$$

where

$$e_{v_s} = \begin{cases} \sum_{m=1}^{n_{v_s}} e_{v_{s,m}}(T_v) & \text{for molecules,} \\ 0 & \text{for atoms,} \end{cases}$$

and

$$e_{v_{s,m}}(T') = \frac{\bar{R}}{M_s} \frac{\theta_{v_{s,m}}}{\exp\left(\theta_{v_{s,m}}/T'\right) - 1}$$

 n_{v_s} : number of vibrational modes of species s ($n_{v_s} = 0$ for atoms) $\theta_{v_{s,m}}$: characteristic vibrational temperature of mode m of species seno et al. Code Verification for Flows in Thermochemical Nonequilibrium 11 / 51 (f) Sandia National Laboratories Equations Spatial Accuracy 000000

Translational–Vibrational Energy Exchange

Landau–Teller model:

$$Q_{t-v} = \sum_{s=1}^{n_s} \rho_s \sum_{m=1}^{n_{v_s}} \frac{e_{v_{s,m}}(T) - e_{v_{s,m}}(T_v)}{\langle \tau_{s,m} \rangle}$$

Translational-vibrational energy relaxation time for mode m of species s:

$$\langle \tau_{s,m} \rangle = \left(\sum_{s'=1}^{n_s} \frac{y_{s'}}{\tau_{s,m,s'}} \right)^{-1} + \left[\left(N_{\rm A} \sum_{s'=1}^{n_s} \frac{\rho_{s'}}{M_{s'}} \right) \sigma_{v_s} \sqrt{\frac{8}{\pi} \frac{\bar{R}T}{M_s}} \right]^{-1}$$

where

$$y_s = \frac{\rho_s/M_s}{\sum_{s'=1}^{n_s} \rho_{s'}/M_{s'}}, \quad \tau_{s,m,s'} = \frac{\exp\left[a_{s,m,s'}\left(T^{-1/3} - b_{s,m,s'}\right) - 18.42\right]}{p'}, \quad \sigma_{v_s} = \sigma'_{v_s}\left(\frac{50,000 \text{ K}}{T}\right)^2$$

p': pressure in atmospheres.

 $a_{s,m,s'}$ and $b_{s,m,s'}$: vibrational constants for mode m of species s with colliding species s' $N_{\rm A}$: Avogadro constant

 σ_{v_e} : collision-limiting vibrational cross section

 $\sigma'_{v_{*}}$: collision-limiting vibrational cross section at 50,000 K.



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Chemical Kinetics

Mass production rate per volume for species s:

$$\dot{w}_s = M_s \sum_{r=1}^{n_r} (\beta_{s,r} - \alpha_{s,r}) (R_{f_r} - R_{b_r})$$

Forward and backward reaction rates for reaction r:

$$R_{f_r} = \gamma k_{f_r} \prod_{s=1}^{n_s} \left(\frac{1}{\gamma} \frac{\rho_s}{M_s}\right)^{\alpha_{s,r}} \quad \text{and} \quad R_{b_r} = \gamma k_{b_r} \prod_{s=1}^{n_s} \left(\frac{1}{\gamma} \frac{\rho_s}{M_s}\right)^{\beta_{s,r}}$$

Forward and backward reaction rate coefficients:

$$k_{f_r}(T_c) = C_{f_r} T_c^{\eta_r} \exp\left(- heta_r/T_c
ight) \qquad ext{and} \qquad k_{b_r}(T) = rac{k_{f_r}(T)}{K_{e_r}(T)}$$

Equilibrium constant for reaction r:

$$K_{e_r}(T) = \exp\left[A_{1_r}\left(\frac{T}{10,000 \text{ K}}\right) + A_{2_r} + A_{3_r}\ln\left(\frac{10,000 \text{ K}}{T}\right) + A_{4_r}\frac{10,000 \text{ K}}{T} + A_{5_r}\left(\frac{10,000 \text{ K}}{T}\right)^2\right]$$

 $\alpha_{s,r}$ and $\beta_{s,r}$: stoichiometric coefficients for species s in reaction r γ : unit conversion factor

 C_{f_r}, η_r, A_{i_r} : empirical parameters

 θ_r : activation energy of reaction r, divided by Boltzmann constant

 T_c : rate-controlling temperature ($T_c = \sqrt{TT_v}$ for dissociation, $T_c = T$ for exchange)



Scope of Code Verification

Conservation of mass, momentum, and energy:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}\right) = -\nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}\right) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}\right) + \mathbf{S}\left(\mathbf{U}\right),$$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \rho \mathbf{v} \\ \rho E \\ \rho e_v \end{cases}, \quad \mathbf{F}_c \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^T \\ \rho \mathbf{v} \mathbf{v}^T \\ \rho E \mathbf{v}^T \\ \rho e_v \mathbf{v}^T \end{bmatrix}, \quad \mathbf{F}_p \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^T \\ \mathbf{0}^T \end{bmatrix}, \quad \mathbf{F}_d \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_v - \mathbf{J}^T \mathbf{h})^T \\ (-\mathbf{q}_v - \mathbf{J}^T \mathbf{e}_v)^T \end{bmatrix},$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad \begin{pmatrix} \rho = \{\rho_1, \dots, \rho_{n_s}\}^T, & \dot{\mathbf{w}} = \{\dot{w}_1, \dots, \dot{w}_{n_s}\}^T : \text{mass production rates per volume,} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad \begin{pmatrix} \rho = \sum_{s=1}^{n_s} \rho_s, & e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s} : \text{ mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R}T, & \mathbf{e}_v = \{e_{v_1}, \dots, e_{v_{n_s}}\}^T : \text{ vibrational energies per mass,} \\ Q_{t-v} : \text{ translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Scope of Code Verification

Conservation of mass, momentum, and energy:

Non-diffusive flux gradients

Thermochemical source term

$$rac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}\left(\mathbf{U}
ight) = - \nabla \cdot \mathbf{F}_{p}\left(\mathbf{U}
ight) + \nabla \cdot \mathbf{F}_{d}\left(\mathbf{U}
ight) + \mathbf{S}\left(\mathbf{U}
ight),$$

where

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \boldsymbol{\rho} \mathbf{v} \\ \boldsymbol{\rho} E \\ \boldsymbol{\rho} e_{\boldsymbol{v}} \end{cases}, \quad \mathbf{F}_{\boldsymbol{c}} \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^{T} \\ \boldsymbol{\rho} \mathbf{v} \mathbf{v}^{T} \\ \boldsymbol{\rho} E \mathbf{v}^{T} \\ \boldsymbol{\rho} e_{\boldsymbol{v}} \mathbf{v}^{T} \end{bmatrix}, \quad \mathbf{F}_{\boldsymbol{p}} \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ \boldsymbol{p} \mathbf{I} \\ \boldsymbol{p} \mathbf{v}^{T} \\ \mathbf{0}^{T} \end{bmatrix}, \quad \mathbf{F}_{\boldsymbol{d}} \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{\boldsymbol{v}} - \mathbf{J}^{T} \mathbf{h})^{T} \\ (-\mathbf{q}_{\boldsymbol{v}} - \mathbf{J}^{T} \mathbf{e}_{\boldsymbol{v}})^{T} \end{bmatrix}$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \{\rho_{1}, \dots, \rho_{n_{s}}\}^{T}, \quad \dot{\mathbf{w}} = \{\dot{w}_{1}, \dots, \dot{w}_{n_{s}}\}^{T} : \text{mass production rates per volume,} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \sum_{s=1}^{n_{s}} \rho_{s}, \quad e_{v} = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{\rho} e_{v_{s}} : \text{mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{M_{s}} \bar{R}T, \quad e_{v} = \{e_{v_{1}}, \dots, e_{v_{n_{s}}}\}^{T} : \text{vibrational energies per mass,} \\ Q_{t-v} : \text{translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Introduction Equations Spatial Accuracy Spatial Results Source Term Source Results Summa ocoococo oco oco oco oco oco oco

Scope of Code Verification

Conservation of mass, momentum, and energy: Non-diffusive flux gradients $\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c} (\mathbf{U}) = -\nabla \cdot \mathbf{F}_{p} (\mathbf{U}) + \nabla \cdot \mathbf{F}_{d} (\mathbf{U}) + \mathbf{S} (\mathbf{U}),$ where Spatial discretization $\mathbf{U} = \begin{cases} \rho \\ \rho \mathbf{v} \\ \rho \mathbf{E} \\ \rho \mathbf{e}_{v} \end{cases}, \quad \mathbf{F}_{c} (\mathbf{U}) = \begin{bmatrix} \rho \mathbf{v}^{T} \\ \rho \mathbf{v} \mathbf{v}^{T} \\ \rho \mathbf{E} \mathbf{v}^{T} \\ \rho \mathbf{e}_{v} \mathbf{v}^{T} \end{bmatrix}, \quad \mathbf{F}_{p} (\mathbf{U}) = \begin{bmatrix} \mathbf{0} \\ \rho \mathbf{I} \\ p \mathbf{v}^{T} \\ \mathbf{0}^{T} \end{bmatrix}, \quad \mathbf{F}_{d} (\mathbf{U}) = \begin{bmatrix} -\mathbf{J} \\ \tau \\ (\tau \mathbf{v} - \mathbf{q} - \mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{h})^{T} \\ (-\mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{e}_{v})^{T} \end{bmatrix},$

 $\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{cases}, \quad \begin{array}{l} \rho = \left\{\rho_1, \dots, \rho_{n_s}\right\}^T, \quad \dot{\mathbf{w}} = \left\{\dot{w}_1, \dots, \dot{w}_{n_s}\right\}^T : \text{ mass production rates per volume,} \\ \rho = \sum_{s=1}^{n_s} \rho_s, \quad e_v = \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} e_{v_s}: \text{ mixture vibrational energy per mass,} \\ p = \sum_{s=1}^{n_s} \frac{\rho_s}{M_s} \bar{R}T, \quad \mathbf{e}_v = \left\{e_{v_1}, \dots, e_{v_{n_s}}\right\}^T: \text{ vibrational energies per mass,} \\ Q_{t-v} : \text{ translational-vibrational energy exchange,} \end{cases}$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



Scope of Code Verification

Conservation of mass, momentum, and energy:

Thermochemical source term

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \mathbf{F}_{c}(\mathbf{U}) = -\nabla \cdot \mathbf{F}_{p}(\mathbf{U}) + \nabla \cdot \mathbf{F}_{d}(\mathbf{U}) + \mathbf{S}(\mathbf{U}),$$

Implementation

$$\mathbf{U} = \begin{cases} \boldsymbol{\rho} \\ \rho \mathbf{v} \\ \rho E \\ \rho e_{v} \end{cases}, \quad \mathbf{F}_{c} \left(\mathbf{U} \right) = \begin{bmatrix} \boldsymbol{\rho} \mathbf{v}^{T} \\ \boldsymbol{\rho} \mathbf{v} \mathbf{v}^{T} \\ \boldsymbol{\rho} E \mathbf{v}^{T} \\ \rho e_{v} \mathbf{v}^{T} \end{bmatrix}, \quad \mathbf{F}_{p} \left(\mathbf{U} \right) = \begin{bmatrix} \mathbf{0} \\ p \mathbf{I} \\ p \mathbf{v}^{T} \\ \mathbf{0}^{T} \end{bmatrix}, \quad \mathbf{F}_{d} \left(\mathbf{U} \right) = \begin{bmatrix} -\mathbf{J} \\ \boldsymbol{\tau} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{h})^{T} \\ (\boldsymbol{\tau} \mathbf{v} - \mathbf{q} - \mathbf{q}_{v} - \mathbf{J}^{T} \mathbf{h})^{T} \end{bmatrix}$$

$$\mathbf{S}\left(\mathbf{U}\right) = \begin{cases} \dot{\mathbf{w}} \\ \mathbf{0} \\ Q_{t-v} + \mathbf{e}_{v}^{T} \dot{\mathbf{w}} \end{cases}, \quad \begin{aligned} \rho &= \{\rho_{1}, \dots, \rho_{n_{s}}\}^{T}, \quad \dot{\mathbf{w}} = \{\dot{w}_{1}, \dots, \dot{w}_{n_{s}}\}^{T} : \text{mass production rates per volume,} \\ \rho &= \sum_{s=1}^{n_{s}} \rho_{s}, \quad e_{v} = \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{\rho} e_{v_{s}} : \text{mixture vibrational energy per mass,} \\ p &= \sum_{s=1}^{n_{s}} \frac{\rho_{s}}{M_{s}} \bar{R}T, \quad \mathbf{e}_{v} = \{e_{v_{1}}, \dots, e_{v_{n_{s}}}\}^{T} : \text{vibrational energies per mass,} \\ Q_{t-v} : \text{translational-vibrational energy exchange,} \end{cases}$$

$$E = \frac{|\mathbf{v}|^2}{2} + \sum_{s=1}^{n_s} \frac{\rho_s}{\rho} \left(c_{\mathcal{V}_s} T + e_{v_s} + h_s^o \right)$$



	Equations	Spatial Accuracy	Spatial Results		Summary 00
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Introduction •

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- Verification Techniques for Spatial Accuracy
 - Spatial Accuracy
 - Solutions
 - Error Norms
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
- Thermochemical-Source-Term Verification Results
- Summary •



Equations Spatial Accuracy 00000

Spatial Accuracy (Steady State)

Governing equations $\mathbf{r}(\mathbf{U}) = \mathbf{0}$

Discretized equations $\mathbf{r}_h(\mathbf{U}_h) = \mathbf{0}$

Discretization error is $\mathbf{e}_h = \mathbf{U}_h - \mathbf{U}_h$

Truncation error is $\boldsymbol{\tau}_h(\mathbf{V}) = \mathbf{r}_h(\mathbf{V}) - \mathbf{r}(\mathbf{V})$

Letting $\mathbf{V} = \mathbf{U}_h$ and adding $\mathbf{r}(\mathbf{U}) = \mathbf{0}$,

 $\boldsymbol{\tau}_h(\mathbf{U}_h) = \mathbf{r}_h(\mathbf{U}_h) - \mathbf{r}(\mathbf{U}_h) + \mathbf{r}(\mathbf{U}) = \mathbf{r}(\mathbf{U}) - \mathbf{r}(\mathbf{U}_h)$

When **r** is linearized w.r.t. **U**, $\mathbf{r}(\mathbf{e}_h) = -\boldsymbol{\tau}_h(\mathbf{U}_h)$



Spatial Accuracy (Steady State)

For p^{th} -order-accurate discretization, truncation error is

$$\boldsymbol{\tau}_h = \mathbf{r}(\mathbf{U}) - \mathbf{r}(\mathbf{U}_h) = \mathbf{C}_{\mathbf{r}} h^p + \mathcal{O}(h^{p+1})$$

h: relative characterization of cell sizes

- Between meshes, with respect to one dimension
- Individual cell sizes may be non-uniform functions of h
- Sufficiently fine meshes \rightarrow asymptotic region $(h^{p+1} \ll h^p)$

$$\mathbf{e}_h = \mathbf{U}_h - \mathbf{U} \approx \mathbf{C}_{\mathbf{U}} h^p$$

 $\mathbf{C_r}$ and $\mathbf{C_U}:$ function of derivative(s) of state vector \mathbf{U}

• Approximately constant between meshes in asymptotic region





Observed accuracy p computed using 2 meshes:





Observed accuracy p computed using 2 meshes:

Coarser mesh (h)

 $e_1 = Ch^p$





Observed accuracy p computed using 2 meshes:

Coarser mesh (h)Finer mesh (h/q)
(q-times as fine in each dimension) $e_1 = Ch^p$ $e_2 = C(h/q)^p$





Observed accuracy p computed using 2 meshes:

Coarser mesh (h)Finer mesh (h/q)
(q-times as fine in each dimension)

$$e_1 = Ch^p \qquad \qquad e_2 = C(h/q)^p$$

\boldsymbol{p} is computed by

$$p \approx \frac{\log |\mathbf{e}_1/\mathbf{e}_2|}{\log q} = \log_q |\mathbf{e}_1/\mathbf{e}_2|$$



		Spatial Accuracy		Source Term		Summary
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Solutions	5					

Need solution to compute error



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				



	Equations 000000	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				
Exact Se	olutions				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\mathrm{Exact}}) = \mathbf{0}$



	$\begin{array}{c} \text{Equations} \\ \text{000000} \end{array}$	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\mathrm{Exact}}) = \mathbf{0}$
- Limited cases



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\mathrm{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000			Summary 00
Solutions						

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\mathrm{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space

Manufactured Solutions


	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\mathrm{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space

Manufactured Solutions

- Do not satisfy original equations: $\mathbf{r}(\mathbf{U}_{\mathrm{MS}}) \neq \mathbf{0}$



	$\begin{array}{c} \text{Equations} \\ \text{000000} \end{array}$	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\text{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space

- Do not satisfy original equations: $\mathbf{r}(\mathbf{U}_{MS}) \neq \mathbf{0}$
- Require source term: $\mathbf{r}_h(\mathbf{U}_h) = \mathbf{r}(\mathbf{U}_{MS})$



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	5				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\text{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space

- Do not satisfy original equations: $\mathbf{r}(\mathbf{U}_{MS}) \neq \mathbf{0}$
- Require source term: $\mathbf{r}_h(\mathbf{U}_h) = \mathbf{r}(\mathbf{U}_{MS})$
- Manufactured to exercise features of interest



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	S				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\text{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space

- Do not satisfy original equations: $\mathbf{r}(\mathbf{U}_{MS}) \neq \mathbf{0}$
- Require source term: $\mathbf{r}_h(\mathbf{U}_h) = \mathbf{r}(\mathbf{U}_{MS})$
- Manufactured to exercise features of interest
- Should be smooth, continuously differentiable functions with generally nonzero derivatives and moderate variations



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	S				

- Negligible implementation effort: $\mathbf{r}(\mathbf{U}_{\text{Exact}}) = \mathbf{0}$
- Limited cases
- Span small subset of application space

- Do not satisfy original equations: $\mathbf{r}(\mathbf{U}_{MS}) \neq \mathbf{0}$
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	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Solutions	S				

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	Equations	Spatial Accuracy	Spatial Results 0000000000000000000	Source Term 000	Summary 00
Error No	orms				



	Equations	Spatial Accuracy	Spatial Results 000000000000000000000000000000000000		Summary 00
Error No	m rms				

• For cell-centered schemes, cell centers vary with mesh refinement



		Spatial Accuracy		Summary
		000000		
Error No	rms			

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless



		Spatial Accuracy				
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Frror No	rng					

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless

Error norms to quantify spatial accuracy: $p = \log_q (\varepsilon_{\alpha_1} / \varepsilon_{\alpha_2})$



Spatial Accuracy Spatial Results 00000

Error Norms

Computing p at a single location in domain has two shortcomings:

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless

Error norms to quantify spatial accuracy: $p = \log_q (\varepsilon_{\alpha_1} / \varepsilon_{\alpha_2})$

• L¹-norm:
$$\varepsilon_{\alpha}^{1} = \|\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})\|_{1} = \int_{\Omega} |\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})| d\Omega$$



Spatial Accuracy Spatial Results 00000

Error Norms

Computing p at a single location in domain has two shortcomings:

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless

Error norms to quantify spatial accuracy: $p = \log_a (\varepsilon_{\alpha_1} / \varepsilon_{\alpha_2})$

• L¹-norm:
$$\varepsilon_{\alpha}^{1} = \|\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})\|_{1} = \int_{\Omega} |\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})| d\Omega$$

– Average error



Error Norms

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- Average error
- Not significantly contaminated by localized deviations (e.g., discontinuities, lower-order boundary conditions)



Spatial Accuracy Spatial Results 00000

Error Norms

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• L¹-norm:
$$\varepsilon_{\alpha}^{1} = \|\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})\|_{1} = \int_{\Omega} |\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})| d\Omega$$

- Average error
- Not significantly contaminated by localized deviations (e.g., discontinuities, lower-order boundary conditions)
- L^{∞} -norm: $\varepsilon_{\alpha}^{\infty} = \|\alpha_h(\mathbf{x}) \alpha(\mathbf{x})\|_{\infty} = \max_{\mathbf{x} \in \Omega} |\alpha_h(\mathbf{x}) \alpha(\mathbf{x})|$



Error Norms

Computing p at a single location in domain has two shortcomings:

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless

Error norms to quantify spatial accuracy: $p = \log_q (\varepsilon_{\alpha_1} / \varepsilon_{\alpha_2})$

- L¹-norm: $\varepsilon_{\alpha}^{1} = \|\alpha_{h}(\mathbf{x}) \alpha(\mathbf{x})\|_{1} = \int_{\Omega} |\alpha_{h}(\mathbf{x}) \alpha(\mathbf{x})| d\Omega$
 - Average error
 - Not significantly contaminated by localized deviations (e.g., discontinuities, lower-order boundary conditions)
- L^{∞} -norm: $\varepsilon_{\alpha}^{\infty} = \|\alpha_h(\mathbf{x}) \alpha(\mathbf{x})\|_{\infty} = \max_{\mathbf{x} \in \Omega} |\alpha_h(\mathbf{x}) \alpha(\mathbf{x})|$
 - Maximum error



Error Norms

Computing p at a single location in domain has two shortcomings:

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless

Error norms to quantify spatial accuracy: $p = \log_q \left(\varepsilon_{\alpha_1} / \varepsilon_{\alpha_2} \right)$

- L¹-norm: $\varepsilon_{\alpha}^{1} = \|\alpha_{h}(\mathbf{x}) \alpha(\mathbf{x})\|_{1} = \int_{\Omega} |\alpha_{h}(\mathbf{x}) \alpha(\mathbf{x})| d\Omega$
 - Average error
 - Not significantly contaminated by localized deviations (e.g., discontinuities, lower-order boundary conditions)
- L^{∞} -norm: $\varepsilon_{\alpha}^{\infty} = \|\alpha_h(\mathbf{x}) \alpha(\mathbf{x})\|_{\infty} = \max_{\mathbf{x} \in \Omega} |\alpha_h(\mathbf{x}) \alpha(\mathbf{x})|$
 - Maximum error
 - Catches localized deviations (expected and **unexpected**)



Spatial Accuracy Spatial Results 00000

Error Norms

Computing p at a single location in domain has two shortcomings:

- For cell-centered schemes, cell centers vary with mesh refinement
- In regions where error vanishes, computed p is meaningless

Error norms to quantify spatial accuracy: $p = \log_a (\varepsilon_{\alpha_1} / \varepsilon_{\alpha_2})$

• L¹-norm:
$$\varepsilon_{\alpha}^{1} = \|\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})\|_{1} = \int_{\Omega} |\alpha_{h}(\mathbf{x}) - \alpha(\mathbf{x})| d\Omega$$

- Average error
- Not significantly contaminated by localized deviations (e.g., discontinuities, lower-order boundary conditions)
- L^{∞} -norm: $\varepsilon_{\alpha}^{\infty} = \|\alpha_h(\mathbf{x}) \alpha(\mathbf{x})\|_{\infty} = \max_{\mathbf{x} \in \Omega} |\alpha_h(\mathbf{x}) \alpha(\mathbf{x})|$
 - Maximum error
 - Catches localized deviations (expected and **unexpected**)
- Without discontinuities, both norms should yield same p



		Spatial Accuracy	Spatial Results			
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Outling						

- Introduction •
- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results - Single-Species Inviscid Flow in Thermochemical Equilibrium – Five-Species Inviscid Flow in Chemical Nonequilibrium
- Verification Techniques for Thermochemical Source Term
- Thermochemical-Source-Term Verification Results



Spatial Results

1D Supersonic Flow using a Manufactured Solution

- One-dimensional domain: $x \in [0, 1]$ m
- Boundary conditions:
 - Supersonic inflow (x = 0 m)
 - Supersonic outflow (x = 1 m)
- 5 uniform meshes: 50, 100, 200, 400, 800 elements
- Solution consists of small, smooth perturbations to uniform flow:

$$\begin{split} \rho(x) &= \bar{\rho} \left[1 - \epsilon \sin(\pi x) \right], \\ u(x) &= \bar{u} \left[1 - \epsilon \sin(\pi x) \right], \\ T(x) &= \bar{T} \left[1 + \epsilon \sin(\pi x) \right], \end{split}$$

 $\bar{\rho} = 1 \text{ kg/m}^3$, $\bar{T} = 300 \text{ K}$, $\bar{M} = 2.5$, $\epsilon = 0.05$





	First-order accurate				nd-order acc	urate	
	Original boundary conditions			Original boundary conditions Corrected boundary co			conditions
Mesh	ρ	u	Т	ρ	u	Т	
1 - 2	1.0008	1.0008	1.0008	2.0313	2.0362	2.0351	
2 - 3	1.0002	1.0002	1.0002	2.0157	2.0184	2.0178	
3-4	1.0001	1.0001	1.0000	2.0079	2.0093	2.0090	
4-5	1.0000	1.0000	1.0000	2.0040	2.0047	2.0045	

Observed accuracy p using L^{∞} -norms of the error



- Two-dimensional domain: $(x,y) \in [0,\,1] \ \mathbf{m} \times [0,\,1] \ \mathbf{m}$
- Boundary conditions:
 - Supersonic inflow (x = 0 m)
 - Supersonic outflow (x = 1 m)
 - Slip wall (tangent flow) (y = 0 m & y = 1 m)
- 5 nonuniform meshes: $25 \times 25 \rightarrow 400 \times 400$
- Solution consists of small, smooth perturbations to uniform flow:

$$\begin{split} \rho\left(x,y\right) &= \bar{\rho}\left[1-\epsilon\sin\left(\frac{5}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ u\left(x,y\right) &= \bar{u}\left[1+\epsilon\sin\left(\frac{1}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ v\left(x,y\right) &= \bar{v}\left[-\epsilon\sin\left(\frac{5}{4}\pi x\right)\left(\sin\left(-\pi y\right)-\right)\right)\right],\\ T(x,y) &= \bar{T}\left[1+\epsilon\sin\left(\frac{5}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right], \end{split}$$

 $\bar{\rho}=1~{\rm kg/m^3},\,\bar{T}=300$ K, $\bar{M}=2.5,\,\epsilon=0.05$





➤ x

 $\rightarrow x$

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0.95

2D Supersonic Flow using a Manufactured Solution



	First-order accurate				Second-order accurate			
	Original boundary conditions				Corrected boundary conditions			
Mesh	ρ	u	v	Т	ρ	u	v	Т
1-2	0.9420	0.9409	0.9721	0.9628	2.0623	1.9188	1.8174	1.8598
2 - 3	0.9850	0.9902	0.9910	0.9874	2.1304	1.9450	1.9221	1.9280
3-4	0.9960	1.0002	0.9924	0.9952	2.0902	1.9603	1.9671	1.9586
4-5	0.9989	1.0009	0.9959	0.9984	2.0128	1.9823	1.9860	1.9809

Observed accuracy p using $L^\infty\text{-norms}$ of the error





2D Supersonic Flow using an Exact Solution

- Two-dimensional domain: $(r,\theta) \in [1,\,1.384] \times [0,\,90]^\circ$
- Boundary conditions:
 - Supersonic inflow ($\theta = 90^{\circ}$)
 - Supersonic outflow ($\theta = 0^{\circ}$)
 - Slip wall (tangent flow) (r = 1 & r = 1.384)
- 6 meshes: $32 \times 8 \rightarrow 1024 \times 256$
- Solution is steady isentropic vortex:

$$\begin{split} \rho(r) &= \rho_i \left[1 + \frac{\gamma - 1}{2} M_i^2 \left(1 - \left(\frac{r_i}{r} \right)^2 \right) \right]^{\frac{1}{\gamma - 1}},\\ u_r(r) &= 0,\\ u_\theta(r) &= -a_i M_i \frac{r_i}{r},\\ T(r) &= T_i \left[1 + \frac{\gamma - 1}{2} M_i^2 \left(1 - \left(\frac{r_i}{r} \right)^2 \right) \right], \end{split}$$

 $\rho_i = 1, a_i = 1, M_i = 2.25, T_i = 1/(\gamma R)$







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Spatial Results

2D Supersonic Flow using an Exact Solution



Observed accuracy p using L^{∞} -norms of the error

1.9879

1.9940

2.0054

2.0029

2.0044

2.0025

1.9972

1.9986

4 - 5

5-6



- Three-dimensional domain: $(x, y, z) \in [0, 1] \text{ m} \times [0, 1] \text{ m} \times [0, 1] \text{ m}$
- Boundary conditions:
 - Supersonic inflow (x = 0 m)
 - Supersonic outflow (x = 1 m)
 - Slip wall (tangent flow) (y = 0 m, y = 1 m, z = 0 m, z = 1 m)
- 5 nonuniform meshes: $25 \times 25 \times 25 \rightarrow 400 \times 400 \times 400$
- Solution consists of small, smooth perturbations to uniform flow: $\rho(x, y, z) = \bar{\rho} \left[1 - \epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y) \right) \left(\sin(\pi z) + \cos(\pi z) \right) \right],$ $u(x, y, z) = \bar{u} \left[1 + \epsilon \sin\left(\frac{1}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y)\right) \left(\sin(\pi z) + \cos(\pi z)\right) \right],$ $\left(\sin(\pi z) + \cos(\pi z)\right)$ $v(x, y, z) = \bar{v} \left[-\epsilon \sin\left(\frac{5}{4}\pi x\right) (\sin(\pi y)) \right]$ $w(x, y, z) = \bar{w} \left[-\epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y)\right) \left(\sin(\pi z)\right) \right]$ $T(x, y, z) = \overline{T} \left[1 + \epsilon \sin\left(\frac{5}{4}\pi x\right) \left(\sin(\pi y) + \cos(\pi y)\right) \left(\sin(\pi z) + \cos(\pi z)\right) \right],$ $\bar{\rho} = 1 \text{ kg/m}^3$, $\bar{T} = 300 \text{ K}$, $\bar{M} = 2.5$, $\epsilon = 0.05$







3D Supersonic Flow using a Manufactured Solution



Mesh	ρ	u	v	w	T
1 - 2	2.0849	1.8731	1.9841	1.7039	1.9404
2 - 3	2.1406	1.9923	1.9295	1.8621	1.9774
3-4	2.0990	2.0115	1.9623	1.9349	1.9922
4 - 5	2.0585	2.0100	1.9820	1.9571	1.9964

Observed accuracy p using L^{∞} -norms of the error

Spatial Results

Five-Species Air Model

5 species: N_2 , O_2 , NO, N, and O

17 reactions:

r	Reaction		Type of Reaction
1–5	$N_2 + \mathcal{M} \leftrightarrows N + N + \mathcal{M},$	$\mathcal{M} = \{\mathrm{N}_2,\mathrm{O}_2,\mathrm{NO},\mathrm{N},\mathrm{O}\}$	Dissociation
6 - 10	$O_2 + \mathcal{M} \leftrightarrows O + O + \mathcal{M},$	$\mathcal{M} = \{N_2, O_2, NO, N, O\}$	Dissociation
11 - 15	$\mathrm{NO} + \mathcal{M} \leftrightarrows \mathrm{N} + \mathrm{O} + \mathcal{M},$	$\mathcal{M} = \{N_2, O_2, NO, N, O\}$	Dissociation
16	$N_2 + O \rightleftharpoons N + NO$		Exchange
17	$NO + O \rightleftharpoons N + O_2$		Exchange





Five-Species Inviscid Flow in Chemical Nonequilibrium

- Two-dimensional domain: $(x,y) \in [0,\,1]$ m $\times [0,\,1]$ m
- Same boundary conditions
- 7 nonuniform meshes: $25\times25\rightarrow1600\times1600$
- Solution consists of small, smooth perturbations to uniform flow

$$\begin{split} \rho_{\mathrm{N}_{2}}\left(x,y\right) &= \bar{\rho}_{\mathrm{N}_{2}}\left[1-\epsilon\sin\left(\frac{5}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ \rho_{\mathrm{O}_{2}}\left(x,y\right) &= \bar{\rho}_{\mathrm{O}_{2}}\left[1+\epsilon\sin\left(\frac{3}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ \rho_{\mathrm{NO}}(x,y) &= \bar{\rho}_{\mathrm{NO}}\left[1+\epsilon\sin\left(-\pi x\right)\left(\sin\left(-\pi y\right)\right)\right)\right],\\ \rho_{\mathrm{N}}\left(x,y\right) &= \bar{\rho}_{\mathrm{N}}\left[1+\epsilon\sin\left(-\pi x\right)\left(\cos\left(\frac{1}{4}\pi y\right)\right)\right],\\ \rho_{\mathrm{O}}\left(x,y\right) &= \bar{\rho}_{\mathrm{O}}\left[1+\epsilon\sin\left(-\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(\frac{1}{4}\pi y\right)\right)\right],\\ u\left(x,y\right) &= \bar{u}\left[1+\epsilon\sin\left(\frac{1}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ v\left(x,y\right) &= \bar{v}\left[-\epsilon\sin\left(\frac{5}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ T\left(x,y\right) &= \bar{T}\left[1+\epsilon\sin\left(\frac{5}{4}\pi x\right)\left(\sin\left(-\pi y\right)+\cos\left(-\pi y\right)\right)\right],\\ T_{v}\left(x,y\right) &= \bar{T}_{v}\left[1+\epsilon\sin\left(\frac{3}{4}\pi x\right)\left(\sin\left(-\frac{5}{4}\pi y\right)+\cos\left(\frac{3}{4}\pi y\right)\right)\right] \end{split}$$





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Introduction	Equations	Spatial Accuracy	Spatial Results	Source Term	Source Results	Summary

2D Supersonic Flow in Thermal Equilibrium using a Manufactured Solution

Variable	Value	Units
$\bar{ ho}_{\mathrm{N}_2}$	0.77	kg/m^3
$\overline{\rho}_{\rm NO}^2$ $\overline{\rho}_{\rm NO}$	$0.20 \\ 0.01$	kg/m^3
$\bar{\rho}_{\rm N}$ $\bar{\rho}_{\rm O}$	$0.01 \\ 0.01$	kg/m ³ kg/m ³
\bar{T}	3500	K
$M = \epsilon$	$2.5 \\ 0.05$	



Mesh	$ ho_{ m N_2}$	$ ho_{\mathrm{O}_2}$	$ ho_{ m NO}$	$ ho_{ m N}$	$ ho_{ m O}$	u	v	T
1 - 2	2.0608	2.1382	2.0698	2.0644	2.1885	1.8425	1.8289	1.7351
2 - 3	2.1161	2.1219	2.1127	2.1072	2.1697	1.8875	1.9220	1.7923
3 - 4	2.0798	2.0813	1.8555	2.0754	2.0971	1.9200	1.9686	1.8525
4 - 5	2.0456	2.0458	1.8917	2.0428	2.0806	1.9522	1.9871	1.9079
5-6	2.0243	2.0243	1.9427	2.0228	2.0529	1.9735	1.9939	1.9485
6-7	2.0125	2.0125	1.9790	2.0118	2.0318	1.9865	1.9969	1.9737

2D MMS, $n_s = 5, T_v = T, \dot{\mathbf{w}} \neq \mathbf{0}$: Observed accuracy p using L^{∞} -norms of the error



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2D Hypersonic Flow in Thermal Nonequilibrium using a Manufactured Solution

Variable	Value	Units
$\bar{ ho}_{ m N_2}$	0.0077	$\rm kg/m^3$
$\bar{ ho}_{\mathrm{O}_2}$	0.0020	$\rm kg/m^3$
$\bar{\rho}_{\rm NO}$	0.0001	$\rm kg/m^3$
$\bar{\rho}_{\rm N}$	0.0001	$\rm kg/m^3$
$\bar{\rho}_{\rm O}$	0.0001	kg/m^3
\overline{T}	5000	Κ
\bar{T}_v	1000	Κ
\overline{M}	8	
ϵ	0.05	



Mesh	$ ho_{ m N_2}$	$ ho_{\mathrm{O}_2}$	$ ho_{ m NO}$	$ ho_{ m N}$	$ ho_{ m O}$	u	v	T	T_v
1 - 2	1.5659	1.6370	1.6555	1.6046	1.5869	1.7742	1.7337	1.7814	1.5545
2 - 3	1.9067	1.6944	1.6986	1.7598	1.8819	1.8916	1.8701	1.8768	1.9150
3-4	1.9868	2.0475	2.0698	2.0477	2.0110	1.9488	1.9357	1.9349	2.0082
4-5	2.0074	1.9941	2.0138	1.9936	2.0089	1.9752	1.9684	1.9672	2.0168
5-6	2.0062	1.9939	2.0004	1.9935	2.0061	1.9879	1.9843	1.9836	2.0111
6-7	2.0037	1.9965	1.9994	1.9962	1.9955	1.9940	1.9922	1.9918	2.0063

2D MMS, $n_s = 5, T_v \neq T, \dot{\mathbf{w}} \neq \mathbf{0}$: Observed accuracy p using L^{∞} -norms of the error



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- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
 - Techniques
 - Distinctive Features
- Thermochemical-Source-Term Verification Results
- Summary



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• $\mathbf{S}(\mathbf{U}) = \begin{bmatrix} \dot{\mathbf{w}}; \mathbf{0}; 0; Q_{t-v} + \mathbf{e}_v^T \dot{\mathbf{w}} \end{bmatrix}$ is algebraic



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Source Term Verification Techniques for Thermochemical Source Term

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 - Compare with independently developed code



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 - For many values of $\{\boldsymbol{\rho}, T, T_v\}$
 - Compare with independently developed code
 - Perform convergence studies on distribution and difference
- For each query, compute symmetric relative difference

$$\delta_{\beta} = 2 \frac{|\beta_{\text{SPARC}} - \beta'|}{|\beta_{\text{SPARC}}| + |\beta'|}$$



Distinctive Features

This is **not** typical low-rigor code-to-code comparison



Distinctive Features



Distinctive Features

This is **not** typical low-rigor code-to-code comparison Distinctive and rigorous features:

• Code is independently developed **internally**



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- Thermochemical-Source-Term Verification Results
 - Samples of $Q_{t-v}(\boldsymbol{\rho},T,T_v)$, $\mathbf{e}_v(\boldsymbol{\rho},T,T_v)$, and $\dot{\mathbf{w}}(\boldsymbol{\rho},T,T_v)$
 - Nonzero Relative Differences in Q_{t-v} and \mathbf{e}_v
 - Nonzero Relative Differences in $\dot{\mathbf{w}}$
 - Convergence History of Relative Differences

• Summary





variable	minimum	mann	Omos	opacing
$ ho_{ m N_2}$	10^{-6}	10^{1}	$\rm kg/m^3$	Logarithmic
$ ho_{\mathrm{O}_2}$	10^{-6}	10^{1}	$\rm kg/m^3$	Logarithmic
$\rho_{\rm NO}$	10^{-6}	10^{1}	$\mathrm{kg/m^{3}}$	Logarithmic
$ ho_{ m N}$	10^{-6}	10^{1}	$\rm kg/m^3$	Logarithmic
$\rho_{\rm O}$	10^{-6}	10^{1}	$\mathrm{kg/m^{3}}$	Logarithmic
T	100	15,000	Κ	Linear
T_v	100	15,000	Κ	Linear

Ranges and spacings for Latin hypercube samples





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- $\delta_{Q_{t-n}} > 10\%$ in 8.7% of simulations







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- $\delta_{Q_{t-v}} > 1\%$ in 29% of simulations







- Relative differences are **not** near machine precision
- $\delta_{Q_{t-v}} > 10\%$ in 8.7% of simulations
- $\delta_{Q_{t-v}} > 1\%$ in 29% of simulations
- $\delta_{\mathbf{e}_v} > 100\%$ for some simulations





Two causes:





Two causes:

- Incorrect lookup table values for vibrational constants
 - For N_2 and O_2 when the colliding species is NO
 - Introduced error in Q_{t-v} for all simulations
 - For high-enthalpy (20 MJ/kg), hypersonic, laminar double-cone flow, 1.4% change in pressure and 2.7% change in heat flux





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 - Introduced error in Q_{t-v} for all simulations
 - For high-enthalpy (20 MJ/kg), hypersonic, laminar double-cone flow, 1.4% change in pressure and 2.7% change in heat flux
- Loose convergence criteria for computing T_v from ρe_v
 - Unsuitable for low values of T_v
 - Introduced errors in Q_{t-v} , \mathbf{e}_v , and $\dot{\mathbf{w}}$ for a few simulations
 - For converged, steady problem, original criteria are acceptable



Source Results 00000000 Corrected Nonzero Relative Differences in Q_{t-v} and \mathbf{e}_{v}

Original lookup table and convergence criteria







Original lookup table and convergence criteria











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• Relative differences are consistent with our expectations





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- $\delta_{Q_{t-v}} < 10^{-10}$ and $\delta_{\mathbf{e}_v} < 10^{-14}$ in all simulations




- Relative differences are consistent with our expectations
- $\delta_{O_{t-n}} < 10^{-10}$ and $\delta_{\mathbf{e}_n} < 10^{-14}$ in all simulations
- $\delta_{Q_{t-v}} > 10^{-12}$ in 48/131,072 simulations





- Relative differences are consistent with our expectations
- $\delta_{O_{t-n}} < 10^{-10}$ and $\delta_{\mathbf{e}_n} < 10^{-14}$ in all simulations
- $\delta_{Q_{t-v}} > 10^{-12}$ in 48/131,072 simulations

-T and T_v have relative difference less than 0.2%





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- $\delta_{Q_{t-n}} < 10^{-10}$ and $\delta_{\mathbf{e}_n} < 10^{-14}$ in all simulations
- $\delta_{Q_{t-v}} > 10^{-12}$ in 48/131,072 simulations
 - -T and T_v have relative difference less than 0.2%
 - In numerator of $\frac{e_{v_{s,m}}(T)-e_{v_{s,m}}(T_v)}{\langle \tau_{s,m} \rangle}$, $e_{v_{s,m}}(T)$ and $e_{v_{s,m}}(T_v)$ share many leading digits



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Corrected Nonzero Relative Differences in Q_{t-v} and \mathbf{e}_v

- Relative differences are consistent with our expectations
- $\delta_{Q_{t-v}} < 10^{-10}$ and $\delta_{\mathbf{e}_v} < 10^{-14}$ in all simulations
- $\delta_{Q_{t-v}} > 10^{-12}$ in 48/131,072 simulations
 - T and T_v have relative difference less than 0.2%
 - In numerator of $\frac{e_{v_{s,m}}(T)-e_{v_{s,m}}(T_v)}{\langle \tau_{s,m} \rangle}$, $e_{v_{s,m}}(T)$ and $e_{v_{s,m}}(T_v)$ share many leading digits
 - Precision lost when computing difference



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Original convergence criteria



Tighter convergence criteria







Original convergence criteria



Tighter convergence criteria



• Relative differences are consistent with our expectations





Original convergence criteria



Tighter convergence criteria



- Relative differences are consistent with our expectations
- $\delta_{\mathbf{w}} < 10^{-9}$ in all simulations





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– Due to precision loss that can occur from subtraction in $\dot{w}_s = M_s \sum_{r=1}^{n_r} (\beta_{s,r} - \alpha_{s,r}) (R_{f_r} - R_{b_r})$





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	Equations	Spatial Accuracy 000000	Spatial Results 0000000000000000000	Source Term 000	$\underset{\bullet \circ}{\text{Summary}}$
Outling					

- Introduction
- Governing Equations
- Verification Techniques for Spatial Accuracy
- Spatial-Discretization Verification Results
- Verification Techniques for Thermochemical Source Term
- Thermochemical-Source-Term Verification Results
- Summary
 - Code-Verification Techniques



Summarv 00

Code-Verification Techniques

- Manufactured and exact solutions
 - Effective approaches for verifying spatial accuracy detected multiple issues
 - Rigorous norms improve effectiveness L^{∞} -norm of error more useful
 - Insufficient for algebraic source terms both evaluations the same
- Thermochemical-source-term approach
 - Effective approach for verifying implementation detected multiple issues
 - Convergence study important to determine whether samples sufficiently span ranges



Introduction Equations Spatial Accuracy Spatial Results Source Term Source Result

Additional Information

B. Freno, B. Carnes, V. Weirs Code-Verification techniques for hypersonic reacting flows in thermochemical nonequilibrium Journal of Computational Physics (2021) arXiv:2007.14376





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This presentation describes objective technical results and analysis. Any

